

Gaussian Elimination

$$3x + 4y = 7 \quad (1)$$

$$2x + 3y = 5 \quad (2)$$

Augmented

$$\left[\begin{array}{cc|c} A & \vec{b} \\ 3 & 4 & 7 \\ 2 & 3 & 5 \end{array} \right]$$

$$A\vec{x} = \vec{b}$$

$$\frac{1}{2} \cdot (1) \quad x + \frac{4}{3}y = \frac{7}{3} \quad (3)$$

$$\xrightarrow{\frac{1}{3}\vec{r}_1 \rightarrow \vec{r}_1} \left[\begin{array}{cc|c} 1 & 0 & \frac{7}{3} \\ 3 & 4 & 7 \\ 2 & 3 & 5 \end{array} \right] \xrightarrow{\text{Row operations}} \left[\begin{array}{cc|c} 1 & 0 & \frac{7}{3} \\ 2 & 3 & 5 \end{array} \right]$$

$$(2) - 2 \cdot (3) \quad \begin{aligned} 2x + 3y &= 5 \\ -(2x + \frac{4}{3}y) &= -2 \cdot \frac{7}{3} \end{aligned} \quad \xrightarrow{-2\vec{r}_1 + \vec{r}_2 \rightarrow \vec{r}_2} \left[\begin{array}{cc|c} 1 & 0 & \frac{7}{3} \\ -2 & 1 & \frac{7}{3} \end{array} \right] \quad \left[\begin{array}{cc|c} 1 & \frac{4}{3} & \frac{7}{3} \\ 2 & 3 & 5 \end{array} \right] = \left[\begin{array}{cc|c} 1 & \frac{4}{3} & \frac{7}{3} \\ 0 & 1 & \frac{1}{3} \end{array} \right]$$

$$\Leftrightarrow \frac{1}{3}y = \frac{1}{3}$$

$$\Leftrightarrow y = 1 \quad (4)$$

$$(4) \rightarrow (3) \quad x = 1$$

$$\left[\begin{array}{cc|c} 1 & \frac{4}{3} & \frac{7}{3} \\ 0 & 1 & \frac{1}{3} \end{array} \right] \left[\begin{array}{c} x \\ y \end{array} \right] = \left[\begin{array}{c} \frac{7}{3} \\ \frac{1}{3} \end{array} \right] \quad (*)$$

↑
upper △

$$\left[\begin{array}{cc|c} 1 & 0 & \frac{7}{3} \\ 0 & 1 & \frac{1}{3} \end{array} \right], \quad \left[\begin{array}{cc|c} 1 & 0 & \frac{7}{3} \\ -2 & 1 & \frac{1}{3} \end{array} \right]$$

elementary row operations

Type 1:

$$\left[\begin{array}{cccc|c} 1 & & & & & 0 \\ & 1 & & & & 0 \\ & & 1 & & & 0 \\ & 0 & & 1 & & 0 \\ & & & & 1 & 0 \\ & & & & & 1 \end{array} \right]$$

$$\alpha \vec{r}_i \rightarrow \vec{r}_i \quad \alpha > 0$$

Type 2:

$$\left[\begin{array}{cccc|c} 1 & & & & & 0 \\ & 1 & & & & 0 \\ & & 1 & & & 0 \\ & -\alpha & 1 & & & 0 \\ & & & 1 & & 0 \\ & & & & 1 & 0 \\ & & & & & 1 \end{array} \right] = \left[\begin{array}{cccc|c} 1 & & & & & 0 \\ & 1 & & & & 0 \\ & & 1 & & & 0 \\ & +\alpha & 1 & & & 0 \\ & & & 1 & & 0 \\ & & & & 1 & 0 \\ & & & & & 1 \end{array} \right]$$

$$\vec{r}_i - \alpha \vec{r}_j \rightarrow \vec{r}_i$$

Both are invertible

Solving $A\vec{x} = \vec{b} \Leftrightarrow \underbrace{E_1 \cdots E_n}_{\text{st}} A\vec{x} = \underbrace{E_1 \cdots E_n \vec{b}}_{\vec{c}}$

$$\vec{U}\vec{x} = \vec{c}$$

where \vec{U} is upper triangular (see $(*)$)

Then \vec{x} can be obtained by back substitution.

BFS $\xrightarrow{\text{ERO's}} \text{BFS}$

Eg 3.1 Observations

(1) ERO recorded in last n columns.

$$A = (R_i | I)$$



$$\underbrace{E_1 \cdots E_i}_{E} A = (U_i | V_i) \text{ tableau } i$$



$$EA = (U_i | V_i)$$



$$E(R_i | I) = (U_i, V_i) \Rightarrow E = V_i$$

Eg Tableau 3

$$\left(\begin{array}{ccc|ccc} 1 & 0 & -\frac{1}{5} & \frac{3}{5} & \frac{1}{5} & 0 \\ 0 & 1 & -\frac{1}{5} & \frac{2}{5} & -\frac{1}{5} & 0 \\ 0 & 0 & \frac{1}{5} & \frac{1}{5} & \frac{3}{5} & 1 \end{array} \right) \quad T_3$$

$$= \underbrace{E_2 \cdots E_1}_{E} \left(\begin{array}{ccc|ccc} 1 & 1 & -1 & 1 & 0 & 0 \\ 2 & 3 & 1 & 0 & 1 & 0 \\ -1 & 2 & -1 & 0 & 0 & 1 \end{array} \right) \quad T_1$$

$$\Rightarrow E = \left(\begin{array}{ccc|c} \frac{3}{5} & \frac{1}{5} & 0 & 0 \\ \frac{2}{5} & -\frac{1}{5} & 0 & 0 \\ -\frac{1}{5} & \frac{3}{5} & 1 & 0 \end{array} \right)$$

(ii) B_i are columns of A corresponding to \vec{e}_j in tableau i.

Tableau i

$$\left(\times \vec{e}_{i_1} \times \vec{e}_{i_2} \times \dots \times \vec{e}_{i_n} \times \dots \right)$$

Since $\underbrace{E_1 \dots E_r}_E A = \left(\times \vec{e}_{i_1} \times \vec{e}_{i_2} \times \dots \times \vec{e}_{i_n} \times \dots \right)$

$$A = E^{-1} \left(\times \vec{e}_{i_1} \times \vec{e}_{i_2} \times \dots \times \vec{e}_{i_n} \times \dots \right)$$

$$\Rightarrow E^{-1} = (\vec{a}_{i_1}, \vec{a}_{i_2}, \dots, \vec{a}_{i_n})$$

Since $B_j = (\vec{a}_{i_1}, \dots, \vec{a}_{i_n})$

$$\therefore A = B_j \left(\times \vec{e}_{i_1} \times \vec{e}_{i_2} \times \dots \times \vec{e}_{i_n} \times \dots \right)$$

||

$$\sum_i$$

Eg. Tableau 3

$x_1 \quad x_2 \quad x_6$	$\left(\begin{array}{cc ccc} 1 & 0 & x & x & x & 0 \\ 0 & 1 & x & x & x & 0 \\ 0 & 0 & x & x & x & 1 \end{array} \right)$
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Current basic soltn is x_1, x_2, x_6

$$\underbrace{E_1 \dots E_r}_E A = \left(\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right) \Rightarrow A = E^{-1} \left(\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right)$$

$$\Rightarrow E^{-1} = (\vec{a}_1, \vec{a}_2, \vec{a}_6) = B_3$$

as x_1, x_2, x_6 are basic variables

$$(ii) \text{ If } E_0 \cdots E_i [A | \vec{b}] = [\vec{\Sigma}_i | \vec{y}_0]$$

then $\vec{y}_0 = B_i^{-1} \vec{b} = \vec{x}_{B_i}$ the basic solution corresponding to basic matrix B_i

Pf: $\underbrace{E_0 \cdots E_i}_{E} [A | \vec{b}] = [\vec{\Sigma}_i | \vec{y}_0]$

$$\Rightarrow E \vec{b} = \vec{y}_0$$

$$\Rightarrow \vec{y}_0 = B_i^{-1} \vec{b} \quad (\text{as } E^T = B_i \text{ observation (ii)})$$

Recall. $A \vec{x} = (B_i R_i) \begin{pmatrix} \vec{x}_{B_i} \\ \vec{0} \end{pmatrix} = \vec{b}$

$$\Rightarrow B_i \vec{x}_{B_i} = \vec{b} \Rightarrow \vec{x}_{B_i} = B_i^{-1} \vec{b} = \vec{y}_0$$

Eg. $\left(\begin{array}{ccc|cc|c} 1 & 1 & -1 & 1 & 0 & 0 \\ 2 & -3 & 1 & 0 & 1 & 0 \\ -1 & 2 & -1 & 1 & 0 & 1 \end{array} \right) \rightsquigarrow \left(\begin{array}{ccc|cc|c} 1 & 0 & x_1 & x_2 & x_3 & x_6 \\ 0 & 1 & x_1 & x_2 & x_3 & x_5 \\ 0 & 0 & x_1 & x_2 & x_3 & x_4 \end{array} \right)$

$\underbrace{A}_{\vec{b}}$ $\underbrace{\vec{\Sigma}_3}_{\vec{y}_0}$

$$\Rightarrow \left(\begin{array}{ccc|cc|c} 1 & 1 & -1 & 1 & 0 & 0 \\ 2 & -3 & 1 & 0 & 1 & 0 \\ -1 & 2 & -1 & 1 & 0 & 1 \end{array} \right) \left(\begin{array}{c} \frac{18}{5} \\ \frac{7}{5} \\ 0 \\ 0 \\ 0 \\ \frac{9}{5} \end{array} \right) = \left(\begin{array}{c} 5 \\ 3 \\ 1 \\ \vec{b} \\ \vec{x} \end{array} \right)$$

In fact $A \vec{x} = B_3 \vec{\Sigma}_3 \vec{x} = B_3 (\vec{e}_1 \vec{e}_2 \vec{e}_3) \left(\begin{array}{c} \frac{18}{5} \\ \frac{7}{5} \\ 0 \\ 0 \\ 0 \\ \frac{9}{5} \end{array} \right)$

$$= B_3 I_3 \left(\begin{array}{c} \frac{18}{5} \\ \frac{7}{5} \\ 0 \\ 0 \\ 0 \\ \frac{9}{5} \end{array} \right) = B_3 \vec{y}_0 = B_3 B_3^{-1} \vec{b} = \vec{b}$$

$$\because E \vec{b} = \vec{y}_0$$

$$\Rightarrow B_3^{-1} \vec{b} = \vec{y}_0$$

Gaussian Elimination in Simplex Algorithm

P.5

$$A = [N; \overset{B_1}{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}]$$

$$= B_1 [B_1^{-1} N | I]$$

$$= B_1 \bar{Y}_1$$

$$B_1 = [1 \dots]$$

$$= [\vec{e}_1, \vec{e}_2, \dots, \vec{e}_m] = I$$

Suppose x_{B_r} is leaving and x_j is entering, i.e. replace \vec{e}_r by \vec{a}_j

If by ERO:

$$\underbrace{E_2 \dots E_1}_{C^{-1}} A = [\vec{u}_1, \vec{u}_2, \dots, \vec{u}_{j-1}, \overset{\overset{0}{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}}{\vec{e}_r}, \vec{u}_{j+1}, \dots, \vec{u}_{n-m}; \vec{e}_1, \dots, \vec{e}_{r-1}, \vec{u}_r, \vec{e}_{r+1}, \dots, \vec{e}_m] \quad (1)$$

$$\text{Note that } B_2 = [\vec{e}_1, \vec{e}_2, \dots, \vec{e}_{r-1}, \overset{\overset{0}{\vec{a}_j}}{\vec{e}_r}, \vec{e}_{r+1}, \dots, \vec{e}_m]$$

$$\text{and } A = B_2 \bar{Y}_2$$

What is \bar{Y}_2 ?

$$(1) \Rightarrow A = C [\vec{u}_1, \vec{u}_2, \dots, \vec{u}_{j-1}, \vec{e}_r, \dots, \vec{u}_{n-m} | \vec{e}_1, \dots, \vec{u}_r, \dots, \vec{e}_m] \quad (2)$$

$$\Leftrightarrow \left\{ \begin{array}{l} \vec{a}_j = C \vec{e}_r \\ \vec{e}_1 = C \vec{e}_1 \\ \vdots \\ \vec{e}_m = C \vec{e}_m \end{array} \right. \Leftrightarrow C = [\vec{e}_1, \vec{e}_2, \dots, \vec{e}_{r-1}, \vec{a}_j, \vec{e}_{r+1}, \dots, \vec{e}_m] = B_2 \quad (3)$$

$$(3) + (2) \Rightarrow A = B_2 [\vec{u}_1, \dots, \vec{u}_{j-1}, \vec{e}_r, \dots, \vec{u}_{n-m} | \vec{e}_1, \dots, \vec{u}_r, \dots, \vec{e}_m]$$

$\Downarrow \bar{Y}_2'' \neq$

Simplex Tableau

$$A\vec{x} = \vec{b}$$

$$[N | B] \begin{bmatrix} \vec{x}_N \\ \vec{x}_B \end{bmatrix} = \vec{b} \quad (1) \quad \vec{x}_N = \vec{0} \quad (2)$$

$$[\vec{c}_N^T | \vec{c}_B^T] \begin{bmatrix} \vec{x}_N \\ \vec{x}_B \end{bmatrix} = x_0 \quad (3)$$

$$(1) \Rightarrow \underbrace{[B^{-1}N | I]}_{Y} \begin{bmatrix} \vec{x}_N \\ \vec{x}_B \end{bmatrix} = B^{-1}\vec{b}$$

$$\Rightarrow \vec{x}_B = B^{-1}\vec{b} - B^{-1}N \vec{x}_N \quad (4)$$

$$\stackrel{(2)}{\Rightarrow} \vec{x}_B = B^{-1}\vec{b}$$

$$(3) \Rightarrow \vec{c}_N^T \vec{x}_N + \vec{c}_B^T (B^{-1}\vec{b} - B^{-1}N \vec{x}_N) = x_0$$

$$\Rightarrow (\vec{c}_N^T - \vec{c}_B^T B^{-1}N) \vec{x}_N + \vec{c}_B^T B^{-1}\vec{b} = x_0 \quad (5)$$

$$\Rightarrow x_0 = \underbrace{\vec{c}_B^T B^{-1}\vec{b}}_{\text{current value}} \quad (6)$$

a constant. (does not depend on \vec{x}_B or \vec{x}_N)

Simplex Tableau

Y

$$\left[\begin{array}{c|c|c} \overbrace{B^{-1}N} & \overbrace{I} & \\ \hline -(\vec{c}_N^T - \vec{c}_B^T) & 0 & \end{array} \right] \begin{bmatrix} \vec{x}_N \\ \vec{x}_B \end{bmatrix} = \begin{bmatrix} \vec{B}^{-1}\vec{b} \\ \vec{c}_B^T B^{-1}\vec{b} \end{bmatrix}$$

Current \vec{x}_B
Current x_0

Simplex
Tableau :

$$\left[\begin{array}{c|c|c} \overbrace{B^{-1}N}^{\text{Non basic}} & \overbrace{I}^{\text{basic}} & \vec{B}^{-1}\vec{b} \\ \hline -(\vec{c}_N^T - \vec{c}_B^T) & 0 & \vec{c}_B^T B^{-1}\vec{b} \end{array} \right]$$

Current solution
Current x_0

$$X_0 = 3X_1 + X_2 + 3X_3 + 0X_4 + 0X_5 + 0X_6$$

$$\left\{ \begin{array}{l} 2X_1 + X_2 + X_3 + X_4 = 2 \\ X_1 + 2X_2 + 3X_3 + X_5 = 5 \\ 2X_1 + 2X_2 + X_3 + X_6 = 6 \\ X_1, X_2, X_3, X_4, X_5, X_6 \geq 0 \end{array} \right.$$

To:

$$\begin{pmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \\ X_5 \\ X_6 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 2 \\ 5 \\ 6 \end{pmatrix}$$

$$X_0 = 3X_1 + X_2 + 3X_3 + 0X_4 + 0X_5 + 0X_6 = 0$$

T₁:

$$\begin{pmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \\ X_5 \\ X_6 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 0 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$X_0 = ?X_1 + 0X_2 + ?X_3 + ?X_4 + 0X_5 + 0X_6$$

express X_2 in terms of X_1, X_3 & X_4

$$X_2 = 2 - 2X_1 - X_3 - X_4$$

$$X_0 = 3X_1 + (3 - 2X_1 - X_3 - X_4) + 3X_3 + 0X_4 + 0X_5 + 0X_6 +$$

$$= X_1 + 0X_2 + 2X_3 - X_4 + 0X_5 + 0X_6 +$$

$\underbrace{}_{= 0} + 2$